

# INJECTION/ SUCTION EFFECTS ON AN OSCILLATORY FLOW IN A ROTATING POROUS CHANNEL

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**Abstract**—The purpose of the paper is to analyse the effects of injection/suction on an oscillatory flow of a viscous incompressible fluid in a rotating horizontal porous channel. The fluid is injected with constant velocity through the lower stationary plate and is being sucked simultaneously with the same constant velocity through the upper plate oscillating in its own plane about a non-zero constant mean velocity. A closed form solution has been obtained and the effects of injection/suction on the resultant velocities and shear stresses for steady and unsteady flows have been studied.

**Keywords:** Oscillatory, Rotating, Porous Channel, Injection/ Suction

## INTRODUCTION

All fluid phenomena on earth involve rotation to a greater or lesser extent. Those in which rotation is an absolutely essential factor include the large scale circulation in the atmosphere and oceans, and so many other flows with small scale circulation. In the last few years a number of studies have appeared in the literature on rotating flows viz. Vidyanidhu and Nigam (1967) Gupta (1972) Jana and Datta (1977). Injection/ suction effects have also been studied extensively for horizontal porous plate in rotating frame of references by Gupta (1972a) Mazumder(1976) Mazumder *et al.* (1976) Soundalgekar and Pop (1973) for different physical situation. Recently, Mazumder (1991) studied an oscillatory Ekman boundary layer flow bounded by two horizontal flat plates, one of which is oscillating about a non-zero constant mean velocity and the other at rest. An alternative solution to this problem is later given by Ganapathy (1994). By taking hydro magnetic effect and oscillatory flow into account Singh *et al.* (2000, 2005, 2009) further improved the analysis. In the present paper it is proposed to study the injection/ suction effects on the oscillatory flow in a horizontal porous channel in a rotating system.

## MATHEMATICAL ANALYSIS

An unsteady flow of a viscous, incompressible fluid is considered between two parallel porous horizontal plates distance  $d$  apart. A constant injection velocity,  $w_0$ , is applied at the lower stationary plate and the same constant suction velocity,  $w_0$ , is applied at the upper plate which is oscillating in its own plane with a velocity  $U^*(t^*)$  about a non-zero constant mean velocity  $U_0$ . Choose the origin on the lower plate lying in  $x^* - y^*$  plane and  $x^*$ -axis parallel to the direction of motion of the upper plate. The  $z^*$ -axis taken perpendicular to the planes of the plates, is the axis of rotation about which the entire system is rotating with a constant angular velocity  $\Omega^*$ . Since the plates are infinite in extent, all the physical quantities except the pressure, depend only on  $z^*$  and  $t^*$ . Denoting the velocity components  $u^*, v^*, w^*$  in the  $x^*, y^*, z^*$

directions, respectively, the flow in the rotating system is governed by the following equations:

$$w_z^* = 0, \tag{1}$$

$$u_t^* + w^* u_z^* = -p_x^* / \rho + \nu u_{zz}^* + 2\Omega^* v^*, \tag{2}$$

$$v_t^* + w^* v_z^* = -p_y^* / \rho + \nu v_{zz}^* - 2\Omega^* u^*, \tag{3}$$

Where,  $\nu$  is the Kinematic viscosity,  $t$  is the time,  $\rho$  is the density and  $p^*$  is the modified pressure. The boundary conditions for the problem are

$$\left. \begin{aligned} u^* = v^* = 0, \quad w^* = w_0, \quad \text{at } z^* = 0, \\ u^* = U^*(t^*) = U_0(1 + \varepsilon \cos \omega^* t^*), \\ v^* = 0, \quad w^* = w_0, \quad \text{at } z^* = d, \end{aligned} \right\} \tag{4}$$

Where,  $\omega^*$  is the frequency of oscillations and  $\varepsilon$  is a very small positive constant.

The integration of the continuity equation (1) under boundary conditions (4) for  $w^*$  gives,  $w^* = w_0$ . Substituting  $w^* = w_0$ . and eliminating the modified pressure gradient, under the usual boundary layer approximations, equations (2) and (3) reduce to

$$u_t^* + w_0 u_z^* = \nu u_{zz}^* + U_t^* + 2\Omega^* v^*, \tag{5}$$

$$v_t^* + w_0 v_z^* = \nu v_{zz}^* - 2\Omega^*(u^* - U^*). \tag{6}$$

Introducing the following non-dimensional quantities

$\eta = z^* / d$ ,  $t = \omega^* t^*$ ,  $u = u^* / U_0$ ,  $v = v^* / U_0$ ,  $\Omega = \Omega^* d^2 / \nu$  the rotation parameter,  $\omega = \omega^* d^2 / \nu$  the frequency parameter and  $s = w_0 d / \nu$  the injection/suction parameter, we get

$$\omega u_t + s u_\eta = u_{\eta\eta} + \omega U_t + 2\Omega v, \tag{7}$$

$$\omega v_t + s v_\eta = v_{\eta\eta} - 2\Omega(u - U), \tag{8}$$

and the corresponding transformed boundary conditions become:

$$\left. \begin{aligned} u = v = 0 & \quad \text{at } \eta = 0, \\ u = U(t) = 1 + \varepsilon \cos t, \quad v = 0 & \quad \text{at } \eta = 1. \end{aligned} \right\} \tag{9}$$

Equation (7) and (8) can now be combined into a single equation, by introducing a complex function  $q = u + iv$ , as

$$\omega q_t + s q_\eta = q_{\eta\eta} + \omega U_t - 2i\Omega(q - U), \tag{10}$$

and the boundary conditions (9) can also be written in complex notations as:

$$\left. \begin{aligned} q &= 0 && \text{at } \eta = 0, \\ q &= U(t) = 1 + \frac{\varepsilon}{2}(e^{it} + e^{-it}) && \text{at } \eta = 1. \end{aligned} \right\} \quad (11)$$

In order to solve equation (10) subject to the boundary conditions (11), we look for a solution of the form

$$q(\eta, t) = q_0(\eta) + \frac{\varepsilon}{2} \{q_1(\eta)e^{it} + q_2(\eta)e^{-it}\} \quad (12)$$

Substituting (12) into (10) and (11) and comparing the harmonic and nonharmonic terms, we get

$$q_0'' - sq_0' - l^2 q_0 = -l^2, \quad (13)$$

$$q_1'' - sq_1' - m^2 q_1 = -m^2, \quad (14)$$

$$q_2'' - sq_2' - n^2 q_2 = -n^2, \quad (15)$$

with corresponding transformed boundary conditions

$$\left. \begin{aligned} q_0 &= q_1 = q_2 = 0 && \text{at } \eta = 0, \\ q_0 &= q_1 = q_2 = 1 && \text{at } \eta = 1, \end{aligned} \right\} \quad (16)$$

Where,  $l^2 = i2\Omega$ ,  $m^2 = i(2\Omega + \omega)$  and  $n^2 = i(2\Omega - \omega)$ .

The solutions of equations (13) to (15) under the boundary conditions (16) are obtained as:

$$q_0(\eta) = 1 - (e^{(r_1+r_2)\eta} - e^{(r_2+r_1)\eta}) / (e^{r_1} - e^{r_2}), \quad (17)$$

$$q_1(\eta) = 1 - (e^{(r_3+r_4)\eta} - e^{(r_4+r_3)\eta}) / (e^{r_3} - e^{r_4}), \quad (18)$$

$$q_2(\eta) = 1 - (e^{(r_5+r_6)\eta} - e^{(r_6+r_5)\eta}) / (e^{r_5} - e^{r_6}), \quad (19)$$

Where,

$$\begin{aligned} r_1 &= (s + \sqrt{s^2 + 4l^2})/2, & r_2 &= (s - \sqrt{s^2 + 4l^2})/2, & r_3 &= (s + \sqrt{s^2 + 4m^2})/2, \\ r_4 &= (s - \sqrt{s^2 + 4m^2})/2, & r_5 &= (s + \sqrt{s^2 + 4n^2})/2, & r_6 &= (s - \sqrt{s^2 + 4n^2})/2, \end{aligned}$$

## RESULTS AND DISCUSSION

Now for the resultant velocities and the shear stresses of the steady and unsteady flow, we write,

$$u_0(\eta) + iv_0(\eta) = q_0(\eta) \quad (20)$$

And

$$u_1(\eta) + iv_1(\eta) = q_1(\eta)e^{it} + q_2(\eta)e^{-it} \quad (21)$$

The solution (17) corresponds to the steady part which gives  $u_0$  as the primary and  $v_0$  as the secondary velocity components. The amplitude and the phase difference due to these primary and secondary velocities for the steady flow are given by

$$R_0 = \sqrt{u_0^2 + v_0^2}, \quad \theta_0 = \tan^{-1}(v_0 / u_0) \quad (22)$$

The amplitude or the resultant velocity  $R_0$  and the phase angle  $\theta_0$  for the steady part are shown graphically in figure 1.a, b for two cases of rotation parameter  $\Omega$  small (5, 10) and  $\Omega$  large (25,50) and the injection/suction parameter  $s$ . It is observed from figure 1.a that for small rotation,  $\Omega$ , the resultant velocity  $R_0$  increases with the increase of the injection/suction parameter  $s$  (curves I, II) in the whole width of the channel. However, for large rotation and increase in  $s$  leads to a slight decrease in  $R_0$  near the stationary plate and to a slight increase in  $R_0$  thereafter in the channel (curves IV, V). This figure also reveals that the amplitude  $R_0$  goes on increasing with increasing rotation  $\Omega$  large or small except that it decreases slightly with the increase in large values of the rotation of the system (curves I, III, IV, VI). For large rotations  $R_0$  rises within a very short distance from the stationary plate to the value unity and oscillates about it. Fig. 1.b shows that phase angle  $\theta_0$  for the steady flow increases with increasing injection/suction parameter  $s$  for any value of rotation large or small. It is also clear that with increasing rotation,  $\Omega$ , of the system the phase angle  $\theta_0$  decreases and becomes approximately zero in the upper half of the channel for large rotation (curve IV, VI). A phase lag is observed for large rotation near the upper oscillating plate.

The amplitude and the phase difference of shear stresses at the stationary plate ( $\eta = 0$ ) for the steady flow can be obtained as,

$$\tau_{or} = \sqrt{\tau_{0x}^2 + \tau_{0y}^2}, \quad \theta_{or} = \tan^{-1}(\tau_{oy} / \tau_{ox}), \quad (23)$$

Where,

$$\tau_{ox} + i\tau_{oy} = (\partial q / \partial \eta)_{\eta=0} = (r_1 e^{r_2} - r_2 e^{r_1}) / (e^{r_1} - e^{r_2})$$

Here,  $\tau_{ox}$  and  $\tau_{oy}$  are, respectively, the shear stresses at the stationary plate due to the primary and secondary velocity components. The numerical values for the resultant shear stress  $\tau_{or}$  and the phase angle  $\theta_{or}$ , are listed in table-1. These values in table-1 clearly show that the amplitude  $\tau_{or}$  of the steady shear stress increases with increasing rotation,  $\Omega$ , of the system. An increase in the injection/suction parameter,  $s$ , leads to an increase of  $\tau_{or}$  for small rotations and to a decrease for large rotations. The phase angle,  $\theta_{or}$ , decreases with increasing rotation of the system. For any rotation large or small the phase angle,  $\theta_{or}$ , increases with the increase of injection/suction parameter  $s$ .

The solutions (18) and (19) together give the unsteady part of the flow. The unsteady primary and secondary velocity components  $u_1(\eta)$  and  $v_1(\eta)$ , respectively, for the fluctuating flow can be obtained as

$$u_1(\eta, t) = \{Realq_1(\eta) + Realq_2(\eta)\} \cos t - \{Imq_1(\eta) - Imq_2(\eta)\} \sin t, \quad (24)$$

$$v_1(\eta, t) = \{Realq_1(\eta) - Realq_2(\eta)\} \sin t + \{Imq_1(\eta) + Imq_2(\eta)\} \cos t. \quad (25)$$

The resultant velocity or amplitude and the phase difference of the unsteady flow are given by

$$R_1 = \sqrt{u_1^2 + v_1^2}, \quad \theta_1 = \tan^{-1}(v_1/u_1). \quad (26)$$

For the unsteady part, the resultant velocity or the amplitude,  $R_1$  and the phase angle,  $\theta_1$ , are presented graphically in figure 2.a, b for the two cases of rotation,  $\Omega$  small (5,10) and  $\Omega$  large (25,50). Figure 2.a shows that with increase of injection/suction parameter  $s$  the resultant velocity  $R_1$ , decreases (curves I, II) for small rotations but increases (curves V, VI) for large rotations. For small values of  $\Omega$  the amplitude  $R_1$ , increases (curves I, III) with increase of rotation, however, for large values of rotation  $\Omega$ , the amplitude  $R_1$ , increases (curves V, VII) in the vicinity of the stationary plate but decreases thereafter. Keeping the injection/suction parameter fixed, an increase in the frequency of oscillations  $\omega$  leads to a decrease of the resultant velocity  $R_1$ , (curves I, IV) for small values of rotation but to an increase of  $R_1$ , (curves V, VIII) for large values of rotation.

The Fig. 2.b exhibits that the phase angle  $\theta_1$ , increases (curves I, II) with the increase of injection/suction parameter  $s$  in whole of the channel width for small rotations, however, for large rotations though it increases (curves V, VI) with  $s$  but the phase lead turns into a phase lag near the upper oscillating plate. The phase angle  $\theta_1$ , decreases with the increase of rotation may it be large (curves V, VII) or small (curves I, III). With the increase of the frequency of oscillations  $\omega$  the phase angle  $\theta_1$ , increases except near the oscillating plate where it decreases (curves I, IV) for small rotations. However, for large rotations  $\theta_1$  increases (curves V, VIII) with the increase of  $\omega$  and the phase lead turns into phase lag near the upper oscillating plate where it becomes approximately zero.

For the unsteady part of the flow, the amplitude and the phase difference of shear stresses at the stationary plate ( $\eta=0$ ) can be obtained as

$$\tau_{1x} + i\tau_{1y} = (\partial u_1 / \partial \eta)_{\eta=0} + i(\partial v_1 / \partial \eta)_{\eta=0} \text{ which gives} \quad (27)$$

$$\tau_{1r} = \sqrt{\tau_{1x}^2 + \tau_{1y}^2}, \quad \theta_{1r} = \tan^{-1}(\tau_{1y} / \tau_{1x}). \quad (28)$$

The amplitude  $\tau_{1r}$  of the unsteady shear stresses are shown graphically in figure 3. This figure clearly shows that the amplitude,  $\tau_{1r}$ , increases with increasing rotation  $\Omega$  of the system. For small rotations  $\tau_{1r}$  first decreases (curves I, II) with the increase of injection/suction parameter  $s$  for small frequency of oscillations  $\omega$  but then increases for large frequency of oscillations. For large rotation a clear cut decrease in  $\tau_{1r}$  with  $s$  is observed in this figure (curves IV, V). The numerical value of the phase difference  $\theta_{1r}$  are listed in Table 2. It is interesting to note from these values that the phase lead changes to phase lag with the increasing frequency of oscillations  $\omega$  but at the same

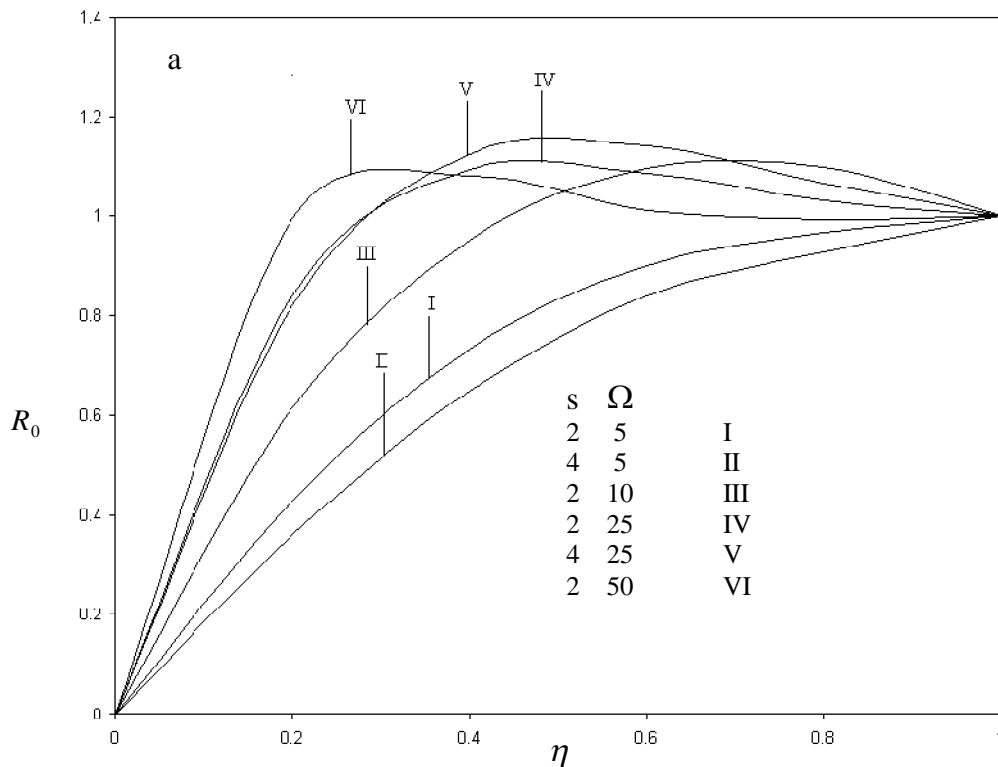
time the increasing rotation  $\Omega$  restricts this effect of  $\omega$ . For small rotations the effect of injection/suction parameter on the phase lead or lag is insignificant. However, for large rotations the phase lead further increases with increasing injection/suction parameter  $s$  for all values of frequency of oscillations  $\omega$  large or small.

**Table 1: Values of  $\tau_{or}$  and  $\theta_{or}$  for Various  $s$  and  $\Omega$**

$s$	$\Omega$	$\tau_{or}$	$\theta_{or}$
2	5	2.5096	1.0275
2	10	3.8268	0.9419
2	25	6.3956	0.8851
2	50	9.3162	0.8560
4	5	2.9631	1.2121
4	25	5.7741	0.9827

**Table 2: Values of  $\theta_{lr}$  for Various  $s$ ,  $\Omega$  and  $\omega$**

$s$	$\Omega$	$\omega$					
		0	5	10	15	20	25
2	5	1.028	1.353	1.466	-1.218	-1.092	-1.028
2	10	0.942	1.086	1.244	1.433	1.496	-1.337
2	25	0.885	0.940	0.995	1.051	1.108	1.168
2	50	0.856	0.883	0.910	0.936	0.963	0.991
4	5	1.212	1.566	-1.276	-1.043	-0.889	-0.791
4	25	0.983	1.043	1.102	1.162	1.223	1.286



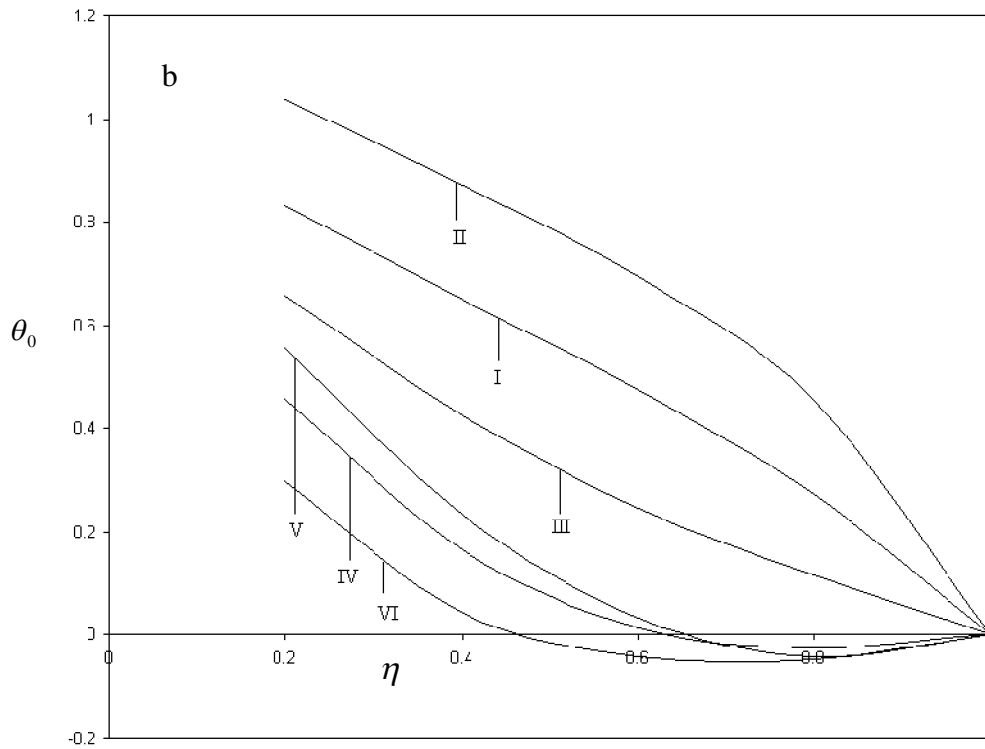
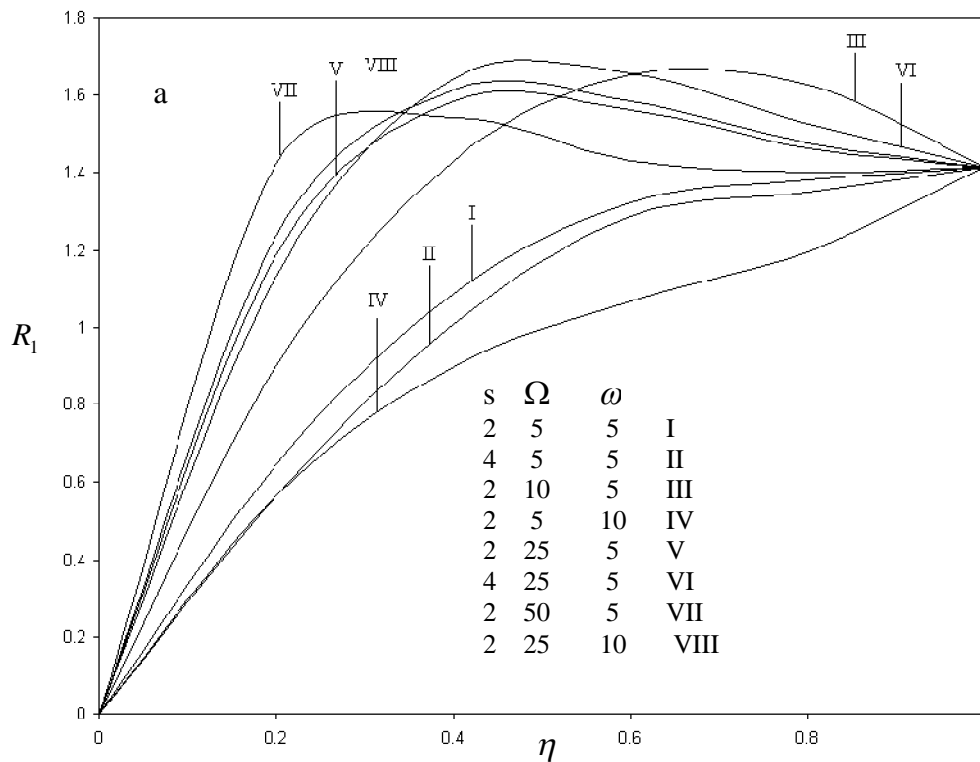


Fig. 1: a,b: Resultant Velocity  $R_0$  and Phase Angle  $\theta_0$  Due to  $u_0$  and  $v_0$



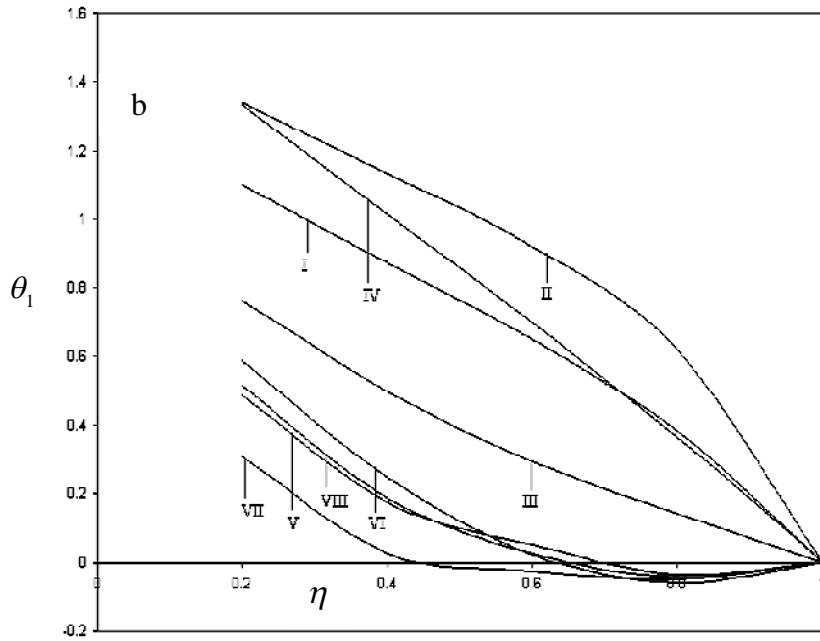


Fig. 2 a,b: Resultant Velocity  $R_1$  and Phase Angle  $\theta_1$  Due to  $u_1$  and  $v_1$

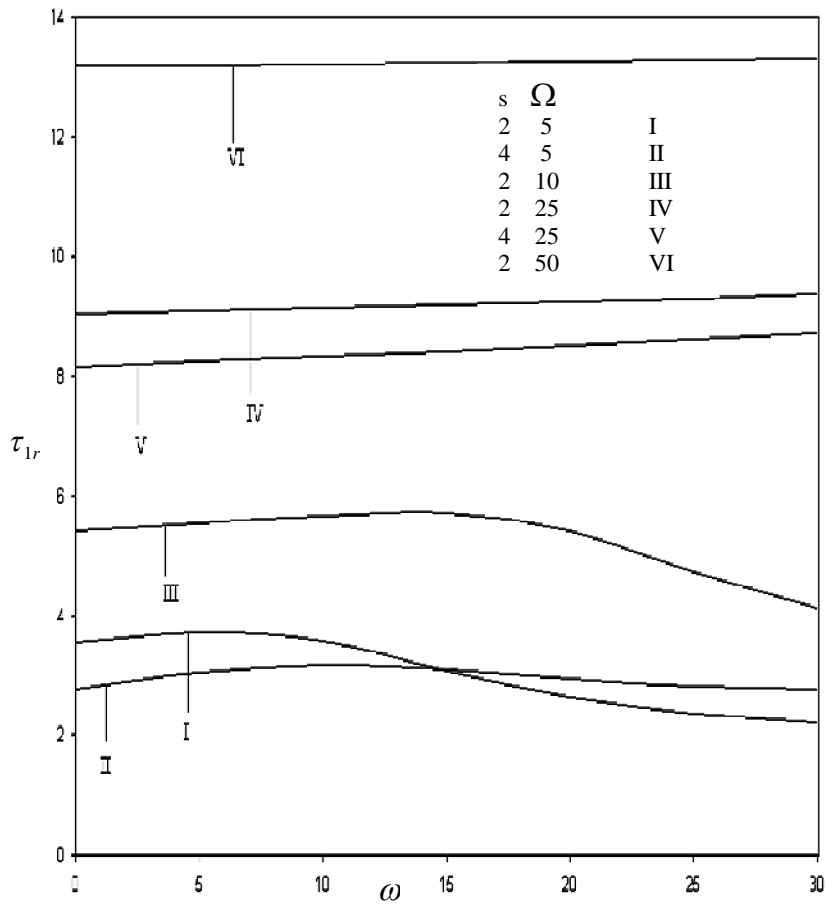


Fig. 3: The Amplitude  $\tau_{1r}$  of Unsteady Shear Stresses for  $t = \pi / 4$



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